Guidesonde: Targeting Meteorological Dropsonde with Optical and In-Situ Sensors, Phase I



Completed Technology Project (2014 - 2014)

Project Introduction

There exists a programmatic need across several government agencies for both UAV and manned aircraft to be able to deploy in-situ observation sensors within areas of scientific interest. These missions include sampling ice at high resolution over the arctic, investigating plumes near active volcanos, measuring ionizing radiation within denied HAZMAT or nuclear emergency areas, and sampling the thermal and momentum fluxes within eyewall of an active hurricane. This latter capability is crucial for the success of future UAS missions such as NASA's Hurricane Severe Storm Sentinel (HS-3). Guidesonde will enable the Global Hawk to loiter at a safe stand off distance, well away from highly turbulent storm areas.

Primary U.S. Work Locations and Key Partners



Organizations Performing Work	Role	Туре	Location
Yankee Environmental Systems,Inc	Lead Organization	Industry	Turners Falls, Massachusetts
Langley Research Center(LaRC)	Supporting Organization	NASA Center	Hampton, Virginia



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Table of Contents

Project Introduction	1
Primary U.S. Work Locations	
and Key Partners	1
Project Transitions	2
Images	2
Organizational Responsibility	
Project Management	2
Technology Maturity (TRL)	2
Technology Areas	3
Target Destinations	3



Small Business Innovation Research/Small Business Tech Transfer

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Primary U.S. Work Locations		
Massachusetts	Virginia	

Project Transitions



June 2014: Project Start



December 2014: Closed out

Closeout Summary: Guidesonde: Targeting meteorological dropsonde with opt ical and in-situ sensors, Phase I Project Image

Closeout Documentation:

• Final Summary Chart Image(https://techport.nasa.gov/file/137504)

Images



Briefing Chart ImageGuidesonde: Targeting
meteorological dropsonde with
optical and in-situ sensors, Phase I
(https://techport.nasa.gov/imag
e/126492)

Organizational Responsibility

Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

Lead Organization:

Yankee Environmental Systems,Inc

Responsible Program:

Small Business Innovation Research/Small Business Tech Transfer

Project Management

Program Director:

Jason L Kessler

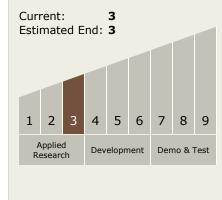
Program Manager:

Carlos Torrez

Principal Investigator:

Mark Beaubien

Technology Maturity (TRL)





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Technology Areas

Primary:

- TX04 Robotic Systems
 TX04.2 Mobility
 TX04.2.4 Surface
 Mobility
- **Target Destinations**

The Sun, Earth, The Moon, Mars, Others Inside the Solar System, Outside the Solar System

